Waves

- A *wave* is a disturbance that propagates through a medium or space.
- Waves transfer energy in the direction of propagation without the bulk transfer of matter.

Examples:

Sound waves, light waves, water waves, earthquakes, string vibrations....

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Waves

Mechanical Waves

Vibrations and Waves

Waves

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Mechanical waves require a medium such as water, air or rock. The motion of these waves are governed by Newton's laws.

- 1.) *Transverse waves* cause the particles of the medium to vibrate *perpendicularly* to the direction of wave motion.
- 2.) *Longitudinal waves* cause the particles of the medium to vibrate *parallel* to the direction of wave motion.

Waves

Electromagnetic Waves

- *Electromagnetic waves* do not require a medium to exist.
- They all travel at the speed of light (3.00 x 10⁸ m/s).

Waves

• They exist only as transverse waves.

Describing Waves

- 1.) *period* (*T*) the shortest time interval during which the wave motion repeats itself. (measured in seconds)
- frequency (f) the number of complete vibrations per second measured at a fixed location. (measured in Hertz = s⁻¹)
- angular frequency (ω) is 2π times the frequency and represents the rate of change of an angular quantity. (measured in radians/s)

$$T = \frac{1}{f} = \frac{2\pi}{\omega}$$
waves

Still Describing Waves

- 4.) wavelength (λ) the shortest distance between points where the wave pattern repeats. (measured in meters)
- 5.) wave number (k) $k = \frac{2\pi}{\lambda} \left(\frac{\text{rad}}{\text{m}}\right)$
- 6.) *amplitude* (A) is the maximum displacement from the rest or equilibrium position. It is an indication of the intensity of the wave.
- 7.) *velocity* (*v*) the speed of the traveling wave (m/s).

$$v = \frac{\lambda}{T} = \lambda f = \frac{\omega}{k} \qquad \qquad \lambda = \frac{v}{f}$$
_{Waves}

Wave Equation

For sinusoidal waves a traveling wave can be described by the following equations:

1.) For waves traveling in the positive *x*-direction:

$$y(x,t) = A\sin(kx - \omega t)$$

2.) For waves traveling in the negative *x*-direction:

$$y(x,t) = A\sin(kx + \omega t)$$

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Waves

Wave Interference

Principle of Superposition - the displacement of the medium by two or more waves is the *sum* of the displacements caused by the individual waves.

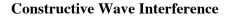
The resultant of the superposition of two or more waves is called *interference*.

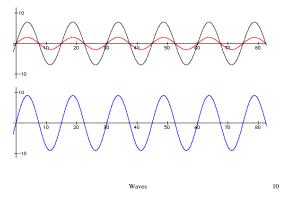
Waves

Constructive Wave Interference

Constructive interference occurs when the wave displacements are in the *same direction*, resulting in a wave with a larger amplitude than the individual components.

Waves

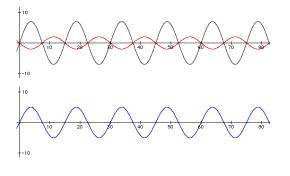




Destructive Wave Interference

Destructive interference occurs when the wave displacements are in the *opposite directions*, resulting in a wave with a smaller amplitude than the individual components.

Destructive Wave Interference



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Wave Interference

In general, the interference of two or more waves is a combination of constructive and destructive interference.

A *node* occurs when there is complete destructive interference.

Waves

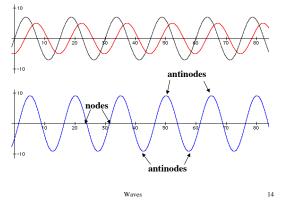
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An *antinode* occurs at the point of maximum constructive interference.





Wave Interactions with Medium Changes

When waves encounter medium changes, the *frequency does not change*.

The *velocity changes* and as a consequence the *wavelength changes*.

Waves

Reflection of Waves

Reflection occurs when a wave is incident upon a medium change.

When a pulse encounters a *more dense medium*, the reflected pulse is *inverted*.

When a pulse encounters a *less dense medium*, the reflected pulse is *not inverted*.

Waves

Standing Waves

Standing waves are the result of the interference of 2 waves traveling in opposite directions with the same amplitude, wavelength, and frequency.

Standing waves have stationary nodes and antinodes.

Standing Waves

Consider the interference of 2 waves moving in opposite directions. The equations are:

$$y_1 = A\sin(kx - \omega t)$$
 and $y_2 = A\sin(kx + \omega t)$

The interference is the sum of these two waves:

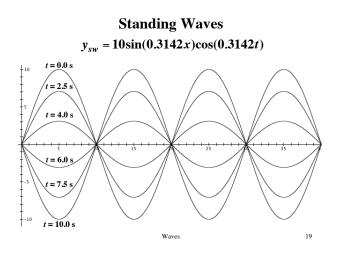
$$y_{sw} = A\sin(kx - \omega t) + A\sin(kx + \omega t)$$

$$y_{sw} = A\sin(kx)\cos(\omega t) - A\cos(kx)\sin(\omega t) +$$

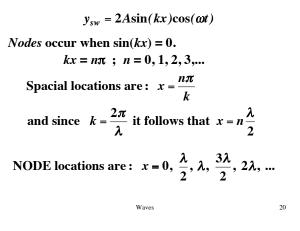
$$A\sin(kx)\cos(\omega t) + A\cos(kx)\sin(\omega t)$$

$$y_{sw} = 2A\sin(kx)\cos(\omega t)$$

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Node Locations on Standing Waves



Antinode Locations on Standing Waves

 $y_{sw} = 2A\sin(kx)\cos(\omega t)$

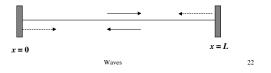
Antinodes occur when $\sin(kx) = \pm 1$ $kx = (n + \frac{1}{2})\pi$: n = 0, 1, 2, 3, ...Spacial locations are : $x = (n + \frac{1}{2})\frac{\pi}{k}$ and since $k = \frac{2\pi}{\lambda}$ it follows that $x = (n + \frac{1}{2})\frac{\lambda}{2}$ ANTINODE locations are : $x = \frac{\lambda}{4}, \frac{3\lambda}{4}, \frac{5\lambda}{4}, \frac{7\lambda}{4}, ...$

Waves on Strings

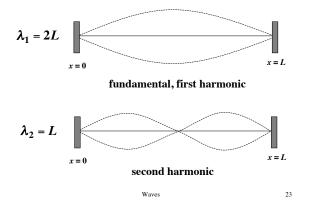
Consider a string of length *L* fixed at both ends.

A *standing wave pattern forms* due to interference of incident and reflected waves from the fixed ends of the strings.

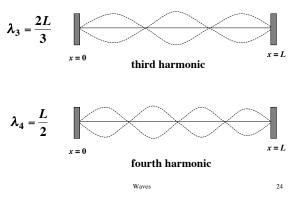
Because the ends are fixed, *nodes* must be present at these locations.







Normal Modes of a String



Waves on Strings

The standing wave patterns generated occur for waves of certain wavelengths that result in nodes at x = 0and x = L.

Therefore, the allowed wavelengths are restricted to:

$$\lambda_n = \frac{2L}{n}$$
 $(n = 1, 2, 3, ...)$
or $\lambda_n = 2L, L, \frac{2L}{3}, \frac{L}{2}, \frac{2L}{5}, ...$

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Frequencies of String Modes

The frequency f of these modes depends upon the wave velocity.

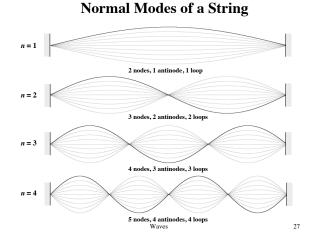
$$f_n = \frac{v}{\lambda_n} = n\frac{v}{2L} = nf_1$$

The lowest mode is when n = 1 and is called the *fundamental frequency*. All other modes are integral multiples of the fundamental frequency.

Waves

$$f_n = f_{1,} 2f_{1,} 3f_{1,} 4f_{1,} \dots$$
 (harmonic overtones)

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Nodes, Anitnodes, and Loops

The n^{th} mode has n + 1 nodes.

The n^{th} mode has n antinodes.

Antinodes are also referred to as *loops*.

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Velocity of Waves on Strings

The *velocity* of a wave on a string depends upon the tension T and the linear density μ of the string.

$$v = \sqrt{\frac{T}{\mu}} \qquad \left(\mu = \frac{m}{L}\right)$$

where:

T = Tension of string (N)

 μ = Linear density of string (kg/m)

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